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1 Introduction

UPC++ is a C++11 library that provides Asynchronous Partitioned Global Address Space (APGAS) programming. It is designed for writing parallel programs that run efficiently and scale well on distributed-memory parallel computers. The APGAS model is single program, multiple-data (SPMD), with each separate thread of execution (referred to as a rank, a term borrowed from MPI) having access to local memory as it would in C++. However, APGAS also provides access to a global address space, which is allocated in shared segments that are distributed over the ranks (see figure 1). UPC++ provides numerous methods for accessing and using global memory, as will be described later in this guide. In UPC++, all operations that access remote memory are explicit, which encourages programmers to be aware of the cost of communication and data movement. Moreover, all remote-memory access operations are by default asynchronous, to enable programmers to write code that scales well even on hundreds of thousands of cores.

Figure 1. APGAS Memory Model.

This guide describes the Berkeley implementation of UPC++, which uses GASNet for communication across a wide variety of platforms, ranging from Ethernet-connected laptops to commodity InfiniBand clusters and supercomputers with custom high-performance networks. GASNet is a language-independent, low-level networking layer that provides network-independent, high-performance communication primitives tailored for implementing parallel global address space languages and libraries such as UPC, UPC++, Co-Array Fortran, Legion, Chapel, and many others. For more information about GASNet, visit http://gasnet.lbl.gov.

Although this implementation of UPC++ uses GASNet, in this guide, only the Installing, Compiling
2 Hello World in UPC++

The following code implements “Hello World” in UPC++:

```cpp
#include <upcxx/upcxx.hpp>
#include <iostream>

// we will assume this is always used in all examples
using namespace std;

int main(int argc, char *argv[]) {
    // setup UPC++ runtime
    upcxx::init();
    // upcxx::rank_me() - get number for this rank
    cout << "Hello world from rank " << upcxx::rank_me() << endl;
    // close down UPC++ runtime
    upcxx::finalize();
    return 0;
}
```

All UPC++ programs need to be initialized with a call to `upcxx::init()` and finalized with a call to `upcxx::finalize()`. These calls set up and tear down the code that implements the UPC++ runtime layer. `upcxx::init()` must be called before any UPC++ features are used, and no UPC++ features should be used after `upcxx::finalize()` is called (until the next call to `upcxx::init()`). Each UPC++ rank has a unique number (running from 0 to N-1, given N ranks), which can be accessed by a call to `upcxx::rank_me()`.

A UPC++ program is run with a fixed number of ranks, and it runs one copy of the program for each rank. In the Hello World example, this program will print out a message from each of the N ranks, for example, if N is 4, then the output could be:

```
Hello World from rank 2
Hello World from rank 0
Hello World from rank 3
Hello World from rank 1
```

Note that there is no ordering enforced between the output from each rank.

3 Installing, Compiling and Running UPC++ Programs

Presented here is a brief description of how to install UPC++ and compile and run UPC++ programs. For more detail, consult the INSTALL.md file that comes with the distribution.

**Installing**

This programming guide assumes that the source code file has been extracted to a directory, `<upcxx-source-path>`. From the top-level of this directory, run the `install` script:
./install <upcxx-install-path>

This will build the UPC++ library and install it to the <upcxx-install-path> directory. Users are recommended to use paths to non-existent or empty directories as the installation path so that uninstallation is as trivial as rm -rf <upcxx-install-path>. Note that the install process downloads the GASNet communication library, so an Internet connection is required.

For Mac installations, the Xcode Command Line Tools need to be installed before invoking install, i.e.:

done-select --install

To build for the compute nodes of a Cray XC, the CROSS environment variable needs to be set before the install command is invoked, i.e. CROSS=cray-aries-slurm. Additionally, because UPC++ does not currently support the Intel compilers (usually the default for these systems), either GCC or Clang must be loaded, e.g.:

module switch PrgEnv-intel PrgEnv-gnu
cd <upcxx-source-path>
CROSS=cray-aries-slurm ./install <upcxx-install-path>

The installer will use the cc and CC compiler aliases of the loaded Cray programming environment.

The list of compatible versions of compilers for the various platforms can be found in the README.md that comes with the distribution, under the section “System Requirements”. The install script checks that the compiler is supported and if not, it aborts with an error message indicating that CXX and CC need to be set to supported compilers, e.g. if a Mac has an old Homebrew install of gcc in /usr/local/bin, CXX and CC will need to be set to the latest Xcode versions in /usr/bin.

### Compiling

To compile against UPC++, use the <upcxx-install-path>/bin/upcxx-meta helper script. This takes a single parameter, one of PPFLAGS, LDFLAGS or LIBFLAGS:

- **PPFLAGS**: Preprocessor flags which will put the UPC++ headers in the compiler’s search path and define macros required by those headers.
- **LDFLAGS**: Linker flags usually belonging at the front of the link command line (before the list of object files).
- **LIBFLAGS**: Linker flags belonging at the end of the link command line. These will make libupcxx and its dependencies available to the linker.

For example, to build the hello world code given previously, using g++, execute:

```
upcxx="<upcxx-install-path>/bin/upcxx-meta"
g++ --std=c++11 hello-world.cpp $(upcxx PPFLAGS) $(upcxx LDFLAGS) $(upcxx LIBFLAGS)
```

For an example, look at the Makefile in the <upcxx-source-path>/example/prog-guide/ directory. That directory also has code for running all of the examples given in the guide. To use the Makefile, first set the UPCXX_INSTALL shell variable to the install path.

UCC++ also supports multithreading within a rank, e.g. using OpenMP. In these cases, to ensure that the application is compiled against a thread-safe UPC++ backend, set UPCXX_THREADMODE=par. Note that this is less efficient than the default, UPCXX_THREADMODE=seq, which enables the use of a UPC++ backend that is synchronization free in most of its internals, so the parallel thread mode should only be used when multithreading within ranks.

In general, the network conduit is automatically set and shouldn’t have to be changed. However, it can be explicitly set using the UPCXX_GASNET_CONDUIT variable, e.g. to set the conduit to UDP:

```
export UPCXX_GASNET_CONDUIT=udp
```

More details about both installation and compilation can be found in the INSTALL.md file in the source code root directory.

### Running
To run a parallel UPC++ application, use the upcxx-run launcher provided in the installation directory:

```
<upcxx-install-path>/bin/upcxx-run -n <ranks> <exe> <args...>
```

This will run the executable and arguments `<exe> <args...>` in a parallel context with `<ranks>` number of UPC++ ranks.

Upon startup, each UPC++ rank creates a fixed-size shared memory heap that will never grow. By default, this heap is 128 MB per rank. This can be adjust by passing a `-shared-heap` parameter to the run script, which takes a suffix of KB, MB or GB; e.g. to reserve 1GB per rank, call:

```
<upcxx-install-path>/bin/upcxx-run -shared-heap 1G -n <ranks> <exe> <args...>
```

There are several options that can be passed to `upcxx-run`. Execute with `-h` to get a list of options.

### 4 A Simple Example of Parallel Computation

We illustrate parallel computation in UPC++ with a simple program that does a Monte Carlo calculation of \( \pi \). This contrived example was chosen because it provides a clear illustration of some of the properties of parallel computation, and has a known correct answer, so we can check our implementation. The value of \( \pi \) can be calculated by repeatedly choosing a random point within the unit square, and counting the percentage of points that fall within the unit circle quadrant (see figure 2). For a unit square with \( r=1 \), the area of the circle quadrant is \( \pi r^2 \approx \pi/4 \). A point \( x,y \) is inside the circle if \( x^2+y^2<1 \). So we can compute the ratio of the number of points inside the circle, \( p_{in} \), to the total number of points, \( p_{tot} \), in order to estimate \( \pi \), i.e. \( \pi = 4 \cdot p_{in}/p_{tot} \).

![Figure 2. Computing \( \pi \).](image)

In the program below, each rank calls a function `hit()` the same number of times (\( my\_trials \)). The total amount of work done is proportional to `upcxx::rank_n()`, which gives the total number of ranks (this is an example of weak scaling). The `hit()` function returns 1 if a randomly chosen point falls within the unit circle quadrant and 0 otherwise. Thus each rank provides an independent estimate of \( \pi \).

The final step is a call to a function, `reduce_to_rank0`, which uses a UPC++ collective function (`upcxx::allreduce`) to sum all the separate results into a single value, so that rank 0 can estimate \( \pi \) and print out the result. The collective function is asynchronous, so we have to wait for the result (the call to `wait()`). The return value for asynchronous calls is described in the Asynchronous Computation section. The collective call also functions as a barrier, so we know that all ranks have completed their computations before we do the final sum.

```cpp
#include <iostream>
#include <cstdlib>
#include <random>
#include <upcxx/upcxx.hpp>

using namespace std;
```
// choose a point at random
int64_t hit()
{
    double x = static_cast<double>(rand()) / RAND_MAX;
    double y = static_cast<double>(rand()) / RAND_MAX;
    if (x*x + y*y <= 1.0) return 1;
    else return 0;
}

// sum the hits to rank 0
// std::int64_t is used to prevent overflows
int64_t reduce_to_rank0(int64_t my_hits)
{
    // wait for a collective reduction that sums all local values
    return upcxx::allreduce(my_hits, plus<int64_t>()).wait();
}

int main(int argc, char **argv)
{
    upcxx::init();
    // each rank gets its own copy of local variables
    int64_t my_hits = 0;
    // the number of trials to run on each rank
    int my_trials = 100000;
    // each rank gets its own local copies of input arguments
    if (argc == 2) my_trials = atoi(argv[1]);
    // initialize the random number generator differently for each rank
    srand(upcxx::rank_me());
    // do the computation
    for (int i = 0; i < my_trials; i++) {
        my_hits += hit();
    }
    // sum the hits and print out the final result
    int64_t hits = reduce_to_rank0(my_hits);
    // only rank 0 prints the result
    if (upcxx::rank_me() == 0) {
        // the total number of trials over all ranks
        int64_t trials = upcxx::rank_n() * my_trials;
        cout << "pi estimate: " << 4.0 * hits / trials << " rank 0 alone: " << 4.0 * my_hits / my_trials << endl;
    }
    upcxx::finalize();
    return 0;
}

When the above code is executed with a small number of iterations-per-rank, for example:
upcxx-run 32 compute-pi 2
It gives output similar to:
pi estimate: 3.4375, rank 0 alone: 2
It can be seen that with low counts per rank, the estimate is poor for a single rank, whereas multiple threads improve the estimate.
In the allreduce collective, std::plus was used to define the arithmetic reduction operator. Unlike MPI, UPC++ does not provide explicit arithmetic operators for collective functions. Instead, UPC++ code is expected to use std functions, such as std::plus or std::multiplies, etc, or to define the operations as lambdas. An important caveat, however, is that only the std functions are eligible for hardware acceleration (should that exist for the given system); lambdas will never be accelerated, and so may not achieve the same performance.

5 Asynchronous Computation

Most communication operations in UPC++ are asynchronous. In the previous example, the collective call, upcxx::allreduce, is asynchronous, so we had to wait to get the result, using wait(). However, we can execute the wait at a later point, allowing us to overlap computation and communication. The function prototype for upcxx::allreduce is:

```cpp
template<
typename T, typename BinaryOp,
typename Completions=decltype(upcxx::operation_cx::as_future())>
RType upcxx::allreduce(T &&value, BinaryOp &&op, upcxx::team &team = upcxx::world(),
    Completions cxx=Completions{});
```

The return type, RType, is dependent on the UPC++ completion object passed to the UPC++ call. The default completion is a UPC++ future, which holds a value (or tuple of values) and a state (ready or not ready). (We’ll use this default completion here, and will return to the subject in detail in the Completions section). When the collective completes, the future becomes ready and can be used to access the results of the collective. The call to wait() in the pi estimation program can be replaced by:

```cpp
upcxx::future<int64_t> my_hits_future = upcxx::allreduce(my_hits, plus<int64_t>());
while (!my_hits_future.ready()) upcxx::progress();
```

First, we get the future object, and then we loop on it until it becomes ready. This loop must include a call to the upcxx::progress function, which progresses the library and transitions futures to a ready state when their corresponding operation completes. This common paradigm is embodied in the wait() method of upcxx::future.

Using futures, the rank waiting for a result can do computation while waiting, effectively overlapping computation and communication, e.g.:

```cpp
upcxx::future<int64_t> my_hits_future = upcxx::allreduce(my_hits, plus<int64_t>());
// do unrelated work here
...
my_hits_future.wait();
```

Note that the upcxx::allreduce has a parameter, upcxx::team. UPC++ supports teams, which are ordered sets of ranks. Collective operations apply to a team. The default team is upcxx::world(), which includes every rank. Currently, this is the only team supported.

An important feature of UPC++ is that there are no ordering guarantees with respect to asynchronous operations, i.e. there is no guarantee that operations will complete in the order they were initiated. This allows for more efficient implementations, but the programmer must not assume any ordering, or errors will result.

6 Remote Procedure Calls

In our calculation of pi, instead of the upcxx::allreduce collective, we could use remote procedure calls (RPCs). An RPC enables a calling rank to send data plus a function to operate on that data to a remote rank. The simplest prototype for the RPC call is:
template<typename Func, typename ...Args>
upcxx::future_invoke_result_t<Func, Args...>
    upcxx::rpc(upcxx::intrank_t recipient, Func &&func, Args&&...args);

This executes function func on rank r and returns the result in a future. The function passed in can be a
lambda, or another function, but note that the function cannot be in a shared library. In the example below,
we use a lambda in an RPC call to replace the upcxx::allreduce collective.

// need to declare a global variable to use with RPC
int64_t hits = 0;
int64_t reduce_to_rank0(int64_t my_hits)
{
    // wait for an rpc that updates rank 0's count
    upcxx::rpc(0, [](int64_t my_hits) { hits += my_hits; }, my_hits).wait();
    // wait until all ranks have updated the count
    upcxx::barrier();
    // hits is only set for rank 0 at this point, which is OK because only
    // rank 0 will print out the result
    return hits;
}

The lambda simply increments the global hits variable on rank 0. The work carried out in the RPC is
done purely on rank 0, and the RPCs are serviced sequentially which ensures there is no possibility of a
race condition. Usually, this work is invoked by the UPC++ runtime inside calls to UPC++ functions. The
mechanism is called progress and is described in more detail in the Progress section. Each rank waits for the
RPC to complete (for the future to complete), and all ranks wait on a barrier (upcxx::barrier()), which
means all ranks will have completed their updates before rank 0 computes and prints the final result.

The prototype for the barrier is:
void upcxx::barrier(upcxx::team &team = upcxx::world());

Like other collectives, the barrier applies to a team, which by default comprises all ranks.

In this specific case, the use of a global upcxx::barrier() is not necessary, as only rank 0 needs to be
aware when all hits have been reduced. Indeed, rank 0 knows how many hits it is expecting, therefore a
global variable hits_counter can be incremented within the RPC. Rank 0 can then poll on the value of
hits_counter and call upcxx::progress until all hits have been received.

// need to declare a global variable to use with RPC
int64_t hits_counter = 0;
int64_t hits = 0;
int64_t reduce_to_rank0(int64_t my_hits)
{
    int64_t expected_hits = upcxx::rank_n();
    // wait for an rpc that updates rank 0's count
    upcxx::rpc(0,
        [](int64_t my_hits) {
            hits += my_hits;
            hits_counter++;
        },
        my_hits).wait();
    // wait until all ranks have updated the count
    if (upcxx::rank_me() == 0)
        while (hits_counter < expected_hits) upcxx::progress();

    // hits is only set for rank 0 at this point, which is OK because only
    // rank 0 will print out the result
return hits;
}

Special care should be taken by developers when using lambda captures. Even in standard C++ functions within a single rank, lambda capture-by-reference (e.g. \([\&foo] (...)\)) can be dangerous without careful attention to object lifetimes. UPC++ imposes several additional constraints:

- When a lambda expression is passed to UPC++, a closure is created by C++ that contains captures of stack variables. That lambda closure is hidden from the calling program while it passes through the UPC++ library, making it difficult for developers to correctly manage the lifetime of any reference-captured variables.

- C++ reference captures are usually implemented by the C++ compiler using pointers. If a lambda closure containing reference captures is sent to another rank (for example, via RPC) those pointers are no longer valid and very likely to cause memory corruption when the references are used at the target. (The same is also true for reference arguments or C++ pointers passed to an RPC function without proper serialization.)

- On distributed memory platforms, variables will often reside in various locations on different ranks due to non-symmetric stacks, making any use of capture-by-reference impossible.

Therefore, when passing C++ lambdas to UPC++ operations, reference captures are strictly prohibited.

7 Global Memory

A global pointer points to a shared object (which is an object allocated within a shared memory segment), and is declared as follows:

```cpp
upcxx::global_ptr<int> gptr = upcxx::new_<int>( upcxx::rank_me() );
```

The call to `upcxx::new_<int>` allocates a new integer on the calling rank’s shared segment, and returns a global pointer (`upcxx::global_ptr`) to the allocated memory. This is illustrated in figure 3, which shows that each rank has its own private pointer (gptr) to an integer in its local shared segment. By contrast, a normal C++ dynamic allocation (`int *mine = new int`) will be in private local memory. Note that we use the integer type in this paragraph as an example, but any type T can be allocated using the `upcxx::new_<T>()` function call.

![Figure 3. Global pointers.](image)

A UPC++ global pointer is fundamentally different from a conventional C++ pointer: it cannot be dereferenced using the * operator; it does not support conversions between pointers to base and derived types; and it cannot be constructed by the C++ `std::addressof` operator. However, UPC++ global pointers support pointer arithmetic and passing a pointer by value.
We can now modify our code for computing $\pi$ to use global memory to get the total number of hits. The first step is for rank 0 to allocate a global pointer `all_hits_ptr` to an array so as to hold all hits values from remote ranks using the `upcxx::new_array` function. This pointer is then broadcast to all ranks, which offset this global pointer by their rank number and store the resulting global pointer in `my_hits_ptr`. Each rank then puts their local hits value to the space pointed by `my_hits_ptr` using the `upcxx::rput` function (remote put). After hitting the `upcxx::barrier`, rank 0 can convert global pointer `all_hits_ptr` to a local pointer (using the `upcxx::global_ptr<T>::local` function), and sum all the values from remote ranks. Finally, rank 0 deallocates the array pointed by `all_hits_ptr` using the `upcxx::delete_array` function.

```c++
int64_t reduce_to_rank0(int64_t my_hits)
{
    // Rank 0 creates an array the size of the number of ranks to store all
    // the global pointers
    upcxx::global_ptr<int64_t> all_hits_ptr = nullptr;
    if (upcxx::rank_me() == 0) {
        all_hits_ptr = upcxx::new_array<int64_t>(upcxx::rank_n());
    }
    // Rank 0 broadcasts the array global pointer to all ranks
    all_hits_ptr = upcxx::broadcast(all_hits_ptr, 0).wait();
    // All ranks offset the start pointer of the array by their rank to point
    // to their own chunk of the array
    upcxx::global_ptr<int64_t> my_hits_ptr = all_hits_ptr + upcxx::rank_me();
    // every rank now puts its own hits value into the correct part of the array
    upcxx::rput(my_hits, my_hits_ptr).wait();
    upcxx::barrier();
    // Now rank 0 gets all the values stored in the array
    int64_t hits = 0;
    if (upcxx::rank_me() == 0) {
        // get a local pointer to the shared object on rank 0
        int64_t *local_hits_ptrs = all_hits_ptr.local();
        for (int i = 0; i < upcxx::rank_n(); i++) {
            hits += local_hits_ptrs[i];
        }
        upcxx::delete_array(all_hits_ptr);
    }
    return hits;
}
```

The remote put function is part of the one-sided communication model supported by UPC++. Also supported is a remote get function, `upcxx::rget`. There are a number of variants of these two functions, the simplest being:

```c++
template<typename T, typename Completions=
 decltype(upcxx::operation_cx::as_future())>
 RType upcxx::rput(T value, upcxx::global_ptr<T> dest, Completions cx=
 Completions{});

template<typename T, typename Completions=
 decltype(upcxx::operation_cx::as_future())>
 RType upcxx::rget(upcxx::global_ptr<T> src, Completions cx=Completions{});
```

These operations initiate transfer of the `value` object to (put) or from (get) the remote rank; no coordination is needed with the remote rank (this is why it is `one-sided`). These operations return a completion object, which defaults to a future that becomes ready when the transfer is complete. In our `reduce_to_rank0` example, we wait on the future before entering the `upcxx::barrier`, i.e.

```c++
upcxx::rput(my_hits, my_hits_ptrs).wait();
```

The type transferred must be serializable, in the sense of the C++ `trivially-copyable` concept. Support for serialization of more complex types will be provided in subsequent versions.
### Downcasting global pointers

In the example above, rank 0 gets the sum of the results put by remote ranks in the array pointed to by `all_hits_ptr`. This array is stored in shared memory with affinity to rank 0; therefore the global pointer can be downcast to a local pointer using the `local` method of `upcxx::global_ptr`, as follows:

```cpp
int64_t *local_hits_ptrs = all_hits_ptr.local();
```

Using this downcast feature, we can treat all shared objects allocated on a rank as local objects. But be aware that it is incorrect to try to downcast a global pointer that is *not* local to this rank. In the previous example, `all_hits_ptr` was allocated by rank 0 *only*:

```cpp
if (upcxx::rank_me() == 0) {
    all_hits_ptr = upcxx::new_array<int64_t>(upcxx::rank_n());
}
```

And so if a rank other than rank 0 downcasts it, that would be an error, e.g. this is `incorrect`:

```cpp
// WRONG - cannot downcast from a non-local global pointer!
int64_t *lp = all_hits_ptr.local();
```

Whereas this would be correct:

```cpp
if (upcxx::rank_me() == 0) {
    int64_t *lp = all_hits_ptr.local();
}
```

Alternatively, a replicated directory of global pointers referencing shared objects allocated cyclically across all ranks can be set up as follows:

```cpp
// declare a vector to store global pointers for all ranks
vector<upcxx::global_ptr<int64_t> > gps(upcxx::rank_n());
// allocate shared memory with affinity to this rank
gps[upcxx::rank_me()] = upcxx::new_<int64_t>();
// broadcast all global pointers to all ranks (gather-to-all)
for (int i = 0; i < upcxx::rank_n(); i++) {
    gps[i] = upcxx::broadcast(gps[i], i).wait();
}
// check for local pointer - should always be true
assert(gps[upcxx::rank_me()].is_local());
// now a rank can downcast its locally allocated global pointer
int *lp = gps[upcxx::rank_me()].local();
// and this is generally false
assert(gps[(upcxx::rank_me() + 1) % upcxx_rank_n()].is_local == false);
```

Note that for checking locality, UPC++ provides an `is_local` method for a global pointer, which will return true if this global pointer is local and can be downcast.

### 8 Allocating and Deallocating Memory in the Shared Segment

In our example above, we used the `upcxx::new_array` function to allocate an array of integers on rank 0. This function not only allocates shared objects, but calls the default class constructor for the objects being allocated. It is paired with `upcxx::delete_array` which calls the destructors. The function prototypes are:

```cpp
template<typename T>
upcxx::global_ptr<T> upcxx::new_array(size_t n);

template<typename T>
void upcxx::delete_array(upcxx::global_ptr<T> g);
```
UPC++ also provides functions for allocating and deallocating single shared objects: `upcxx::new_` and `upcxx::delete_`. As with `upcxx::new_array_`, the `upcxx::new_` function calls the class constructor in addition to allocating memory. However, since it is a single object, arguments can be passed to the constructor, i.e. it does not have to be the default constructor. The prototypes for these functions are:

```cpp
template<typename T, typename ...Args>
upcxx::global_ptr<T> upcxx::new_(Args &&...args);
template<typename T>
void upcxx::delete_(upcxx::global_ptr<T> g);
```

Finally, UPC++ provides functions for allocating and deallocating shared objects without calling constructors and destructors. The `upcxx::allocate` function allocates enough (uninitialized) space for `n` shared objects of type `T` on the current rank, with a specified alignment, and `upcxx::deallocate` frees the memory:

```cpp
template<typename T, size_t alignment = alignof(T)>
upcxx::global_ptr<T> upcxx::allocate(size_t n=1);
template<typename T>
void upcxx::deallocate(upcxx::global_ptr<T> g);
```

9 Distributed Objects

UPC++ provides the concept of distributed object: a single logical object partitioned over a set of ranks (a team), where every rank has the same global name for the object (i.e. a universal name), but its own local value. Distributed objects are created with the `upcxx::dist_object<T>` type, for example:

```cpp
upcxx::dist_object<int64_t> all_hits(upcxx::rank_me());
```

Each rank in a given team must call a constructor collectively for `upcxx::dist_object<T>`, with a value of type `T` representing the rank’s instance value for the object (`upcxx::rank_me()` in the example above).

The need for universal distributed object naming stems primarily from RPC-based communication. If one rank needs to remotely invoke code on a peer’s partition of a distributed object, there needs to be some mutually agreed-upon identifier for referring to that object.

In the `reduce_to_rank0` example below, the distributed object is an integer across all ranks (the default `upcxx::world` team), and the local instance of the object can be set as if it is a regular pointer, as seen in the line `*all_hits = my_hits` (a more compact version is to pass the value to the constructor, i.e. `upcxx::dist_object<int64_t> all_hits(my_hits)`). Although the constructor for a distributed object is collective, there is no guarantee that when the constructor returns on a given rank it will be complete on any other rank. To avoid this hazard, UPC++ provides an interlock to ensure that RPCs accessing a `dist_object` are delayed until the local representative has been constructed. However in this case, we are assigning a value into the `dist_object` after construction, so we insert a barrier to ensure rank 0 won’t access any remote instance of the distributed object until all the ranks have provided their contribution.

```cpp
int64_t reduce_to_rank0(int64_t my_hits)
{
    // declare a distributed on every rank
    upcxx::dist_object<int64_t> all_hits(upcxx::rank_me());
    // set the local value of the distributed object on each rank
    *all_hits = my_hits;
    upcxx::barrier();
    int64_t hits = 0;
    if (upcxx::rank_me() == 0) {
        // rank 0 gets all the values
        for (int i = 0; i < upcxx::rank_n(); i++) {
```
// fetch the distributed object from remote rank i
  hits += fetch(all_hits, i).wait();
}
// ensure that no distributed objects are destructed before rank 0 is done
upcxx::barrier();
return hits;
}

To access the remote value of a distributed object, we define a `fetch` utility function, which takes the name of the distributed object and the rank we want to fetch. This function uses an RPC to get the instance of the distributed object of type `T` from the remote rank (we will use this convenience function several times in subsequent examples).

```cpp
template<typename T>
upcxx::future<T> fetch(upcxx::dist_object<T> &dobj, upcxx::intrank_t rank) {
  return upcxx::rpc(rank, []{
    return *rdobj; }, dobj);
}
```

Note that due to the barrier mentioned above, the RPC is guaranteed to execute on the remote rank after the remote representative of the distributed object has been assigned the `hits` value. However `fetch` does not require this synchronization - the RPC it uses will automatically stall at the target if needed to await construction of the local representative for a `dist_object` appearing as an RPC argument.

In the previous example, all the `fetch` operations are synchronous because of the call to the `wait` method. To achieve maximum performance, UPC++ programs should always take advantage of asynchrony when possible. We illustrate how asynchrony can be used with a powerful UPC++ technique, chaining futures, described in the next section.

### 10 Chaining Futures

When many asynchronous operations are launched, it can be tricky to keep track of all the futures, and wait on all of them for completion. UPC++ provides an elegant solution, allowing futures to be chained, so that the results of one future are dependent on other futures. The example below illustrates how the `hits` for the distributed objects can be accumulated asynchronously using this technique.

```cpp
int64_t reduce_to_rank0(int64_t my_hits) {
  // initialize this rank's part of the distributed object with the local value
  upcxx::dist_object<int64_t> all_hits(my_hits);
  int64_t hits = 0;
  // rank 0 gets all the values asynchronously
  if (upcxx::rank_me() == 0) {
    hits = my_hits;
    upcxx::future<> f = upcxx::make_future();
    for (int i = 1; i < upcxx::rank_n(); i++) {
      // construct the chain of futures
      f = upcxx::when_all(f, fetch(all_hits, i).then(
        [&] (int64_t rhit) { hits += rhit; }));
    }
    // wait for the chain to complete
    f.wait();
  }
  upcxx::barrier();
}
```
return hits;
}

The chaining of futures in the code above can be viewed as an abstract graph, as shown in figure 4. The chain begins with the construction of a trivially ready future on rank 0, using the upcxx::make_future. Rank 0 then loops through each remote rank and calls fetch asynchronously on each rank. The future returned by the fetch call has a callback or completion handler attached to it using the .then method of upcxx::future. The callback is executed on the initiating rank when the fetch completes, and is passed the result of the fetch as a parameter. In this example, the callback is a lambda, which adds the returned hits count for that rank, rhits, to the total hits, hits. Of course, the return value from the .then method call is itself another future. This future is passed to the upcxx::when_all function, in combination with the previous future in the chain, f. The upcxx::when_all constructs a new future representing readiness of all its arguments (in this case f and .then), and returns a future with a concatenated results tuple of the arguments. By setting f to the future returned by when_all, we can extend the chain. Once all the ranks are linked into the chain, rank 0 simply waits on the final future in the chain, i.e. the f.wait() call.

![Figure 4. Graph of future chaining.](image)

It is also possible to keep track of the futures with an array or some other data structure, such as a list. However, chains have several advantages:

- They provide a single future handle to manage an entire logical operation and associated storage. This can simplify composition by enabling an encapsulated communication initiation function to return a single future to the caller rather than, for instance, an array of futures.
- Chains minimize the number of synchronous calls to .wait() needed to complete a group of operations. Without a chain, the code must loop through multiple .wait calls, potentially adding overhead.
- Chains do not leave intermediate futures explicitly instantiated in the application-level memory, thus potentially allowing the storage holding them to be collected as soon as the futures are ready.

### 11 Atomics

UPC++ provides atomic operations on shared objects. This provides another mechanism for the reduce_to_rank0 function in our ongoing example. Each atomic operation works on a global pointer to an approved atomic type, which are std::int32_t, std::uint32_t, std::int64_t and std::uint64_t. In the example below, there is a single shared object allocated on rank 0, and all other ranks atomically increment it.

```cpp
def reduce_to_rank0(int64_t my_hits)
{
    // a global pointer to the atomic counter in rank 0's shared segment
    upcxx::global_ptr<int64_t> hits_ptr =
```
(!upcxx::rank_me() ? upcxx::new_<int64_t>(0) : nullptr);
// rank 0 allocates and then broadcasts the global pointer to all other ranks
hits_ptr = upcxx::broadcast(hits_ptr, 0).wait();
// now each rank updates the global pointer value using atomics for correctness
upcxx::atomic_fetch_add(hits_ptr, my_hits, memory_order_relaxed).wait();
// wait until all ranks have updated the counter
upcxx::barrier();
// once a memory location is accessed with atomics, it should only be
// subsequently accessed using atomics to prevent unexpected results
if (upcxx::rank_me() == 0) {
    return upcxx::atomic_get(hits_ptr, memory_order_relaxed).wait();
} else {
    return 0;
}
}

The atomic fetch and add operation is asynchronous, like most UPC++ communication operations. It returns
a completion object, which defaults to a future, as shown by the prototype definition:

```cpp
template <typename T, typename Completions=decltype(upcxx::operation_cx::as_future())>
RType upcxx::atomic_fetch_add(upcxx::global_ptr<T> p, T val, std::memory_order mo,
                            Completions cxs=Completions{});
```

The only other atomic operations currently supported are put and get:

```cpp
template <typename T, typename Completions=decltype(upcxx::operation_cx::as_future())>
RType upcxx::atomic_put(upcxx::global_ptr<T> p, T val, std::memory_order mo,
                       Completions cxs=Completions{});

template <typename T, typename Completions=decltype(upcxx::operation_cx::as_future())>
RType upcxx::atomic_get(upcxx::global_ptr<T> p, std::memory_order mo,
                       Completions cxs=Completions{});
```

12 A Note on Performance

We have shown five different ways to get the result in the calculation of \( \pi \): reduction with collectives, RPCs,
`rput` with global memory, distributed objects and atomics. These examples illustrate the use of the various
options, but in practice, they would be used in different circumstances, taking performance into account. In
our `reduce_to_rank0` examples, we expect the `upcxx::allreduce` to be the most efficient; all of the others
essentially do a more expensive linear reduction, sometimes with contention.

13 Quiescence

`Quiescence` is a state in which ranks are not doing computations and no messages are currently being transferred
on the network. Quiescence is of particular importance for applications using anonymous asynchronous
operations on which no synchronization is possible on the sender’s side. For example, quiescence may need to
be achieved before destructing resources and/or exiting a `upcxx` computational phase.

To illustrate a simple approach to quiescence, we use the running example of computing \( \pi \). In this case, we
use a version of RPC that does not return a future:

```cpp
template<typename Func, typename ...Args>
void upcxx::rpc_ff(upcxx::intrank_t recipient, Func &&func, Args &&...args);
```
The “ff” stands for “fire-and-forget”. From a performance standpoint, it has the advantage that it does not send a response message to satisfy the future back to the rank which has issued the RPC. However, because of this, there is no guarantee when the RPC will complete, so the only way to determine completion is using additional code. Using upcxx::rpc_ff in the reduce_to_rank0 function, we need to add a counter, n_done, to track completion:

```cpp
int64_t hits = 0;
// counts the number of ranks for which the RPC has completed
int n_done = 0;

int64_t reduce_to_rank0(int64_t my_hits)
{
    // cannot wait for the RPC - there is no return
    upcxx::rpc_ff(0, [](int64_t my_hits) { hits += my_hits; n_done++ }, my_hits);
    if (upcxx::rank_me() == 0) {
        // spin waiting for RPCs from all ranks to complete
        // When spinning, call the progress function to
        // ensure rank 0 processes waiting RPCs
        while (n_done != upcxx::rank_n()) upcxx::progress();
    }
    // wait until all RPCs have been processed (quiescence)
    upcxx::barrier();
    return hits;
}
```

We add a loop that spins waiting for the RPCs from all ranks to be completed. We know that rank 0 has to execute upcxx::rank_n() RPCs (issued by other ranks). The number of RPCs which have been executed is recorded by incrementing n_done in the body of the procedure issued by remote ranks (i.e. in the lambda function launched by the upcxx::rpc_ff call). As long as there are still RPCs to execute, rank 0 will call upcxx::progress to ensure that the upcxx runtime engine executes the RPCs being called on rank 0 (progress is described in more detail in the Progress section). Once n_done is equal to upcxx::rank_n(), rank 0 knows that it is now safe to exit, and can enter the upcxx::barrier on which all the other ranks are currently waiting.

There are many ways to achieve quiescence. When the number of messages to be received is known beforehand, it is possible to implement simple mechanisms such as the one used in our reduce_to_rank0 example. There are also more powerful (and thus more expensive) quiescence algorithms, such as the counting algorithm, that do not require the knowledge of the number of messages/RPCs beforehand. Advanced users requiring this capability should consult the appropriate literature.

### 14 Completions

In the previous examples in this guide, we have relied on futures to inform us about the completion of asynchronous operations. However, UPC++ provides several additional mechanisms for determining completion, including promises, remote procedure calls (RPCs) and local procedure calls (LPCs). Further on in this section, we give an example of RPC completion and promises.

Completions are signaled by events on completion objects. A completion object is constructed by a call to a static member function of one of the completion classes: upcxx::source_cx, upcxx::remote_cx or upcxx::operation_cx. These classes correspond to the different stages of completion of an asynchronous operation: source and remote completions indicate that the resources needed for the operation are no longer in use by UPC++ at the source rank or remote rank, respectively, whereas operation completion indicates that the operation is complete from the perspective of the initiator. As we have seen in the previous examples in this guide, most operations default to notification of operation completion using a future, e.g.:
As shown above, the completion object is constructed as a completion stage combined with a type of completion. There are restrictions on which completion types can be associated with which stages: futures, promises and LPCs are only valid for source and operation completions, whereas RPCs are only valid for remote completions.

It is possible to request multiple completion notifications from one operation using the pipe (\|) operator to combine completion objects. For example, future completion can be combined with RPC completion as follows:

```
auto cxs = (upcxx::remote_cx::as_rpc(some_func) | upcxx::operation_cx::as_future());
```

Several of these completion concepts are demonstrated in the code below. It uses RPC completions, futures and promises. Every asynchronous `upcxx::rput` operation has an associated `RPC completion` which fulfills a `promise` on rank 0, which can be thought of as the `producer` side of the operation, whereas futures are the `consumer` side. In the previous examples of asynchronous calls in this guide, the UPC++ runtime would implicitly create a promise in each case. However, it is possible to explicitly create promises, which are a form of completion.

```cpp
int64_t hits = 0;
upcxx::promise<> prom;
upcxx::global_ptr<int64_t> all_hits_ptr = nullptr;

int64_t reduce_to_rank0(int64_t my_hits)
{
    if (upcxx::rank_me() == 0)
        prom.require_anonymous(upcxx::rank_n());
    if (upcxx::rank_me() == 0)
        all_hits_ptr = upcxx::new_array<int64_t>(upcxx::rank_n());
    // Rank 0 broadcasts the array global pointer to all ranks
    all_hits_ptr = upcxx::broadcast(all_hits_ptr, 0).wait();
    // All ranks offset the start pointer of the array by their rank to point
    // to their own chunk of the array
    upcxx::global_ptr<int64_t> my_hits_ptr = all_hits_ptr + upcxx::rank_me();
    // operation completions
    auto cxs = (upcxx::operation_cx::as_future() |
                upcxx::remote_cx::as_rpc(
                    [](upcxx::intrank_t rank) {
                        hits += *(all_hits_ptr + rank).local();
                        prom.fulfill_anonymous(1);
                    }, upcxx::rank_me()));
    // all ranks try to write to their own part on rank 0 and then accumulate
    auto result = upcxx::rput(my_hits, my_hits_ptr, cxs);
    result.wait();
    upcxx::future<> fut = prom.finalize();
    fut.wait();
    if (upcxx::rank_me() == 0)
        upcxx::delete_array(all_hits_ptr);
    return hits;
}
```

Diving deeper into the details of the example above, rank 0 requires `upcxx::promise<> prom` to be fulfilled by all ranks. Then, it allocates an array to hold all the contributions from remote ranks, and broadcasts the obtained `upcxx::global_ptr`. Then, a `completion cxs` is created, requesting a RPC remote completion and a future operation completion for the subsequent `upcxx::rput` operation. When the `upcxx::rput` is launched, the sender is notified of its completion through the returned future `result`. This means that data
can safely be discarded. On rank 0, when every incoming upcxx::rput operation are complete, a RPC gets executed. This RPC adds the incoming contribution to the global hits counter, and notifies prom that it has been fulfilled by one rank using fulfill_anonymous. When all ranks have executed their rput operation and the associated RPC completion, then prom will be satisfied on rank 0, and the associated future fut will become ready. That way, quiescence is achieved both on the sender side (using the future fut) and the receiver side (using RPC completion and prom).

15 Progress

Progress is a key notion of UPC++ which programmers should be aware of. The UPC++ framework does not use any private rank (thread) to advance its internal state and keep track of any outstanding asynchronous communication. Instead, UPC++ needs the application to give it access to the computing resource from time to time. To do so, UPC++ defines two levels of progress: internal progress and user-level progress. With internal progress, UPC++ may advance its internal state, but no notifications will be delivered to the application. Thus the application cannot easily track this level of progress. With user-level progress, UPC++ may advance its internal state as well as signal completion of user-initiated operations, such as RPCs.

It is very important for any programmer to understand that UPC++ needs to be given access periodically to the CPU. The upcxx::progress function used in our examples provides access to UPC++ explicitly.

upcxx::progress(progress_level lev = progress_level::user)

upcxx::progress is the most important function to make user-level progress, and runs pending RPCs/callbacks on a particular rank. For the programmer, understanding which functions perform progress is crucial, since any invocation of user-level progress may execute RPCs or callbacks. When waiting on a future, user-level progress is also achieved.

Many UPC++ operations have a mechanism to signal completion to the application. However, for performance-oriented applications, UPC++ provides an additional asynchronous operation status indicator called progress-required. This status indicates that further advancements of the current rank or thread’s internal-level progress are necessary so that completion of outstanding operations on remote entities (e.g. notification of delivery) can be reached. Once the progress-required state has been left, UPC++ guarantees that remote ranks will see their side of the completions without any further progress by the current rank. The programmer can query UPC++ when all operations initiated by this rank have reached a state at which they no longer require progress using the following function:

bool upcxx::progress_required();

UPC++ provides a function called upcxx::discharge() which polls on upcxx::progress_required() and asks for internal progress until progress is not required anymore. upcxx::discharge() is equivalent to the following code:

while(upcxx::progress_required())
    upcxx::progress(upcxx::progress_level::internal);

Any application entering a long lapse of inattentiveness (e.g. to perform expensive computations) is highly encouraged to call upcxx::discharge() first.

16 Personas

As mentioned earlier, UPC++ does not use background ranks for progressing asynchronous operations, but rather leaves all control to the user. The rationale is to make UPC++ as lightweight as possible. Instead of relying on its own internal ranks (threads), UPC++ introduces the concept of personas. An object of type upcxx::persona represents a state of the UPC++ library, and UPC++ manages a stack of active personas.
per OS thread. The top of that personas stack is referred to as the current persona. Note that a persona is current to *one and only one* OS thread at a time.

For any UPC++ operation issued by the current persona, the completion notification (e.g. future) will be sent to that same persona. This is still the case even if the active upcxx::persona object is not the current persona anymore by the time the asynchronous operation completes. The key takeaway here is that a upcxx::persona can be used by one rank to issue operations, then passed to another rank (together with the futures corresponding to these operations). That second rank will then be notified of the completion of these operations via their respective futures. This can be used, for instance, to build a *progress thread* — a rank dedicated to progressing asynchronous operations.

UPC++ provides a upcxx::persona_scope class as a means of ensuring that only one OS thread is using a particular persona at a time. Pushing and popping personas from the persona stack (hence changing the current persona) is done with the upcxx::persona_scope type. It is built the following way:

```cpp
template<typename Lock>
upcxx::persona_scope(Lock &lock, upcxx::persona &p);
```

The upcxx::persona_scope requires a thread locking mechanism (the Lock template argument can be any type of lock, such as C++ std::mutex for instance) and the upcxx::persona that needs to be pushed.

As an example, we show how to reimplement the computation of $\pi$ in a master-slave paradigm. Rank 0 is the master: it creates a persona (scheduler_persona), and issues RPCs to all the other ranks within the scope of scheduler persona. Rank 0 then uses OpenMP threading to spawn an additional, secondary OpenMP thread, which has the sole purpose of making progress and accumulating the remote hits. Concurrently, the first OpenMP thread on rank 0 enters a computational phase during which it computes its own hits. Other ranks (slaves) call upcxx::progress until done is set to one by the RPC (See Quiescence ). Note that in this example, we use OpenMP threads, but the example would work with any threading mechanism, such as pthreads or C++-11 threads.

```cpp
#include <mutex>
#include <list>
#include <iostream>
#include <cstdlib>
#include <random>
#include <upcxx/upcxx.hpp>
using namespace std;

// choose a point at random
int64_t hit()
{
    double x = static_cast<double>(rand()) / RAND_MAX;
    double y = static_cast<double>(rand()) / RAND_MAX;
    if (x*x + y*y <= 1.0) return 1;
    else return 0;
}

int done = 0;

int main(int argc, char **argv)
{
    upcxx::init();
    srand(upcxx::rank_me());

    if (upcxx::rank_me() == 0) {
        // the number of trials to run on each rank
```
int64_t trials_per_rank = 100000;
if (argc == 2) trials_per_rank = atoi(argv[1]);
int64_t hits = 0;
int64_t my_hits = 0;

upcxx::persona scheduler_persona;
mutex scheduler_lock;
list<upcxx::future<int64_t> > remote_rpcs;
{
    // Scope block delimits domain of persona scope instance
    auto scope = upcxx::persona_scope(scheduler_lock, scheduler_persona);
    // All following upcxx actions will use scheduler_persona as current
    for (int rank = 1; rank < upcxx::rank_n(); rank++) {
        // launch computations on remote ranks and store the
        // returned future in the list of remote rpcs
        remote_rpcs.push_back(
            upcxx::rpc(rank,
                [](int64_t my_trials) {
                    int64_t my_hits = 0;
                    for (int64_t i = 0; i < my_trials; i++) {
                        my_hits += hit();
                    }
                    done = 1;
                    return my_hits;
                },
                trials_per_rank));
    }
    // scope destructs :
    // - scheduler_persona dropped from active set if it
    // wasn't active before the scope's construction
    // - Previously current persona revived
    // - Lock released
}
#pragma omp parallel sections default(shared)
{
    // This is the computational thread of rank 0
    #pragma omp section
    {
        // do the computation
        for (int64_t i = 0; i < trials_per_rank; i++) {
            my_hits += hit();
        }
    }
    // end omp section
    // Launch another thread to make progress and track completion
    // of the operations
    #pragma omp section
    {
        auto scope = upcxx::persona_scope(scheduler_lock, scheduler_persona);
        while (!remote_rpcs.empty()) {
            upcxx::progress();
            auto it = find_if(remote_rpcs.begin(), remote_rpcs.end(),
                [](upcxx::future<int64_t> & f) {return f.ready();});
            if (it != remote_rpcs.end()) {
                auto &fut = *it;
                }
// accumulate the result
hits += fut.result();
// remove the future from the list
remote_rpcs.erase(it);
}
}
} // end omp section
} // end omp parallel sections

hits += my_hits;
// the total number of trials over all ranks
int64_t trials = upcxx::rank_n() * trials_per_rank;
cout << "pi estimated as " << 4.0 * hits / trials << endl;
} else {
    // other ranks progress until quiescence is reached (i.e. done == 1)
    while (!done) upcxx::progress();
}
upcxx::finalize();
return 0;

In the example above, the hit() function calls the C function rand() which is not thread-safe. However, this is not a bug for this particular example, because only one thread executes the OpenMP section in which the hit function is called. If multiple threads were to perform concurrent operations, the use of thread-safe routines would be required.

17 Advanced Runtime Configuration

There are several environment variables that can be adjusted to fine-tune UPC++. When launching UPC++ jobs with upcxx-run, these variables are automatically set, depending on the parameters passed to the script. Two important parameters are:

- **UPCXX_SEGMENT_MB**: Set the shared memory heap per rank, which defaults to 128MB per rank. This value determines how much shared memory a rank can allocate before that allocation fails, and might need to be tuned on a per-run basis to control how much of the heap is reserved for shared memory versus how much is available for the private heap. The -shared-heap parameter to upcxx-run sets this value.

- **GASNET_MAX_SEGSIZE**: Set the underlying GASNet shared segment, which defaults to 2GB per rank on most systems. Note that this should always be strictly more than the UPCXX_SEGMENT_MB value. upcxx-run will ensure that this value is large enough for the -shared-heap setting, but it will never reduce the value from the default.